**4x4皇后**

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完整性：是（b是确定的）

最优性：是（仅当路径代价是节点深度的非递减函数，一般不是最优的）

时间复杂度：1+b+b²+…bd =O（bd）

空间复杂度：O（bd），将所有节点保存在内存中